

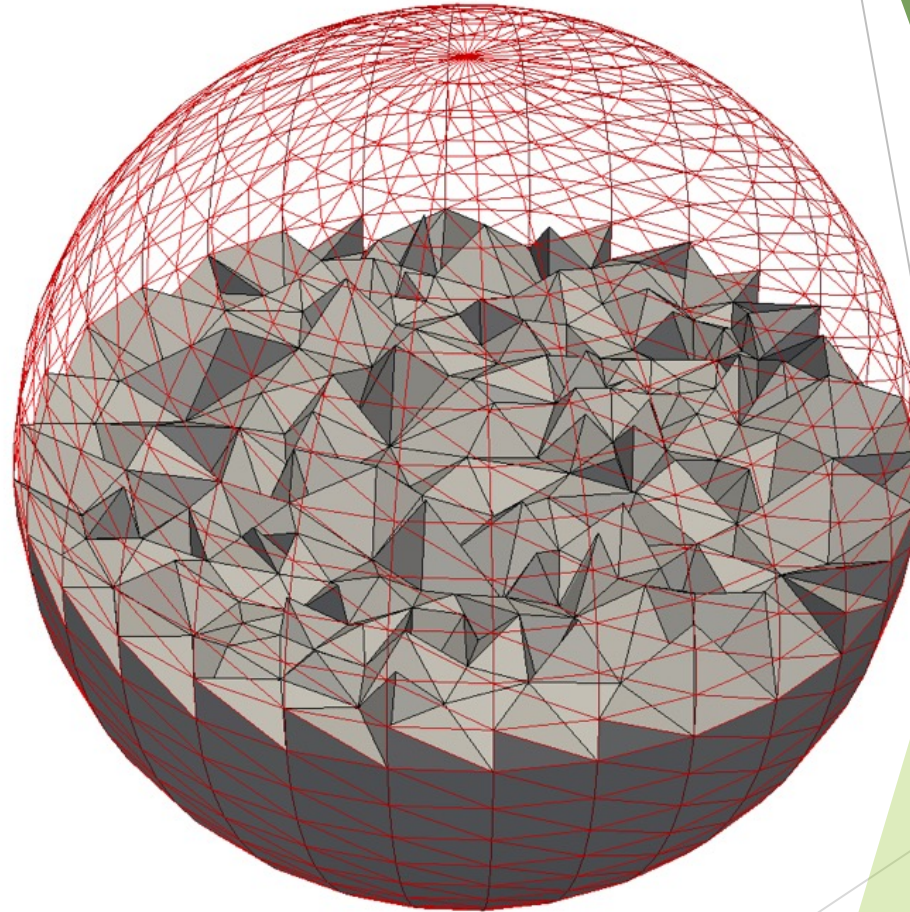


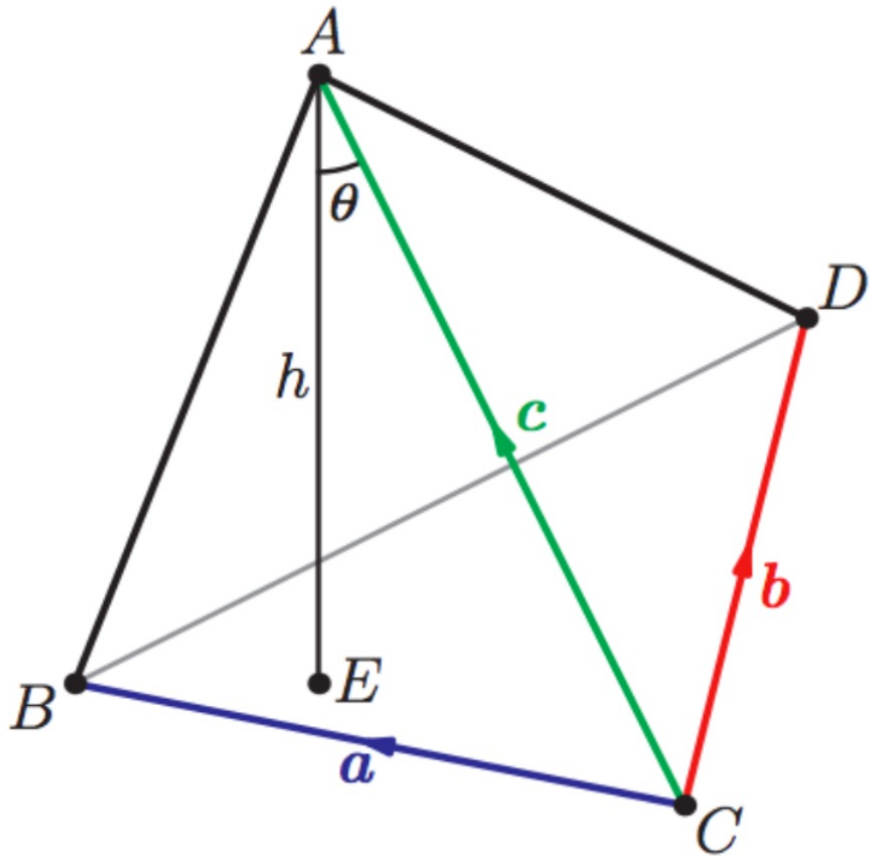
# Tetrahedron Meshing

Nehar Poddar  
Numerical  
Analysis  
Mini - Project 2

# Tetrahedral Volume Meshing

- ▶ The growing importance of subject-specific modeling and simulation in medical applications has increased the need of automatic techniques for creating high-quality meshes directly from medical data.
- ▶ Tetrahedral mesh generation from volumetric data is one of the most intricate problems in modeling and simulation for medical applications.
- ▶ Difficulty comes from several complex steps that are prone to numerical error
- ▶ Steps to generate a volumetric mesh :
  - ▶ Get a 3D object
  - ▶ Iso-surface extraction
  - ▶ Surface mask
  - ▶ Mesh orientation and verification
  - ▶ Oriented surface mesh
  - ▶ Tetrahedral Mesh Generation
  - ▶ Volumetric Mesh





# Volume Of a Tetrahedron

## Vertices:

$$\begin{aligned} A &= (x_1, y_1, z_1) \\ B &= (x_2, y_2, z_2) \\ C &= (x_3, y_3, z_3) \\ D &= (x_4, y_4, z_4) \end{aligned}$$

## Vectors :

$$\begin{aligned} \overrightarrow{AB} &= (x_2 - x_1)i + (y_2 - y_1)j + (z_2 - z_1)k \\ \overrightarrow{AC} &= (x_3 - x_1)i + (y_3 - y_1)j + (z_3 - z_1)k \\ \overrightarrow{AD} &= (x_4 - x_1)i + (y_4 - y_1)j + (z_4 - z_1)k \end{aligned}$$

## Volume of tetrahedron :

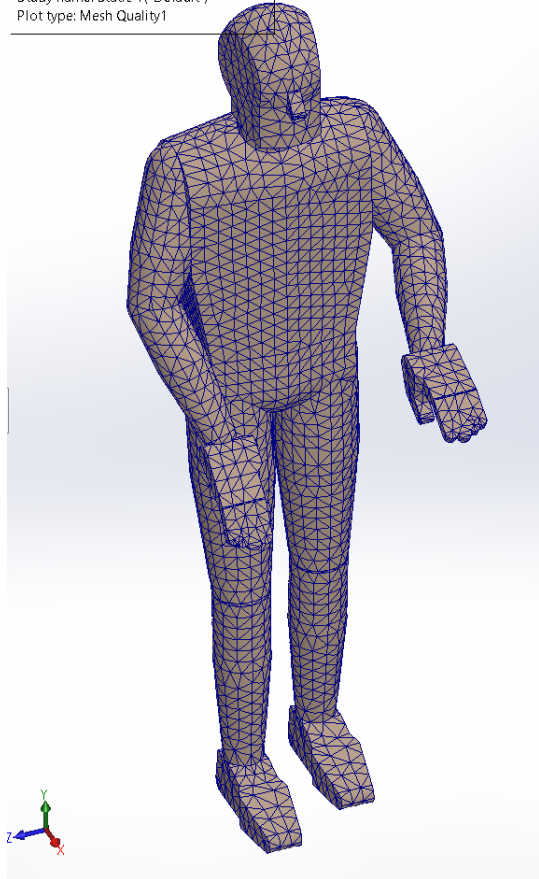
$$\frac{1}{6} \times |\text{scalar triple product of the three vectors}|$$

$$\frac{1}{6} \times | \{ (\overrightarrow{AB} \times \overrightarrow{AC}) \cdot \overrightarrow{AD} \} |$$

$$\frac{1}{6} \times \det \begin{bmatrix} x_2 - x_1 & y_2 - y_1 & z_2 - z_1 \\ x_3 - x_1 & y_3 - y_1 & z_3 - z_1 \\ x_4 - x_1 & y_4 - y_1 & z_4 - z_1 \end{bmatrix}$$

# Algorithm

Model name: Operator Interference.step  
Study name: Static 1(-Default-)  
Plot type: Mesh Quality1



Download CAD file

Surface mesh object in  
SolidWorks

Export to .STL file

Download Pymesh  
Library in Python

From Surface Mesh  
extract **Faces &  
Vertexes**

Using **TETGEN** generate  
the Tetrahedral Volume  
Mesh

From Volume Mesh read  
the **Voxels & Vertexes**

Iterate through each  
Voxel (it comprises of 4  
Vertexes)

Go to the index of the  
Vertex get X,Y,Z  
coordinates of all 4  
Vertexes

From the Coordinates  
get the 3 Vectors

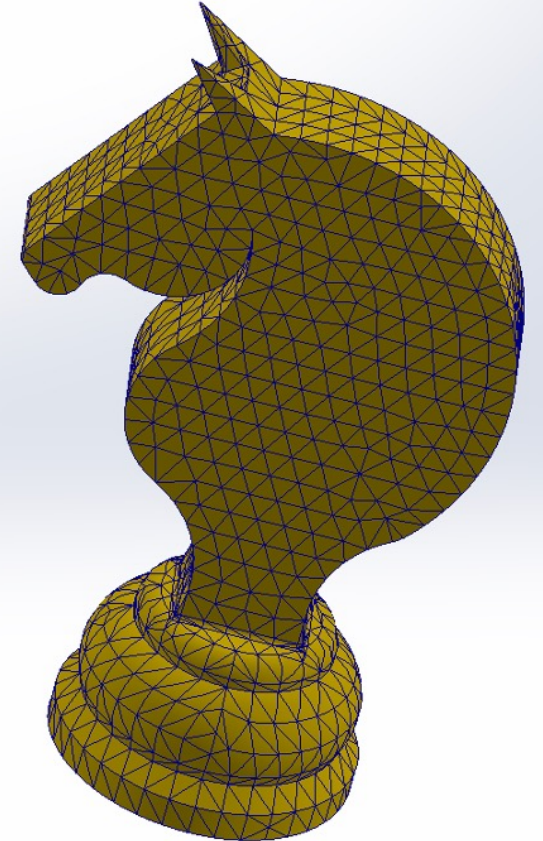
Do **Scalar product** of the  
vectors

Calculate the  
**Determinant** of the  
Matrix and divide by 6 to  
get the volume of each  
Voxel/Tetrahedron

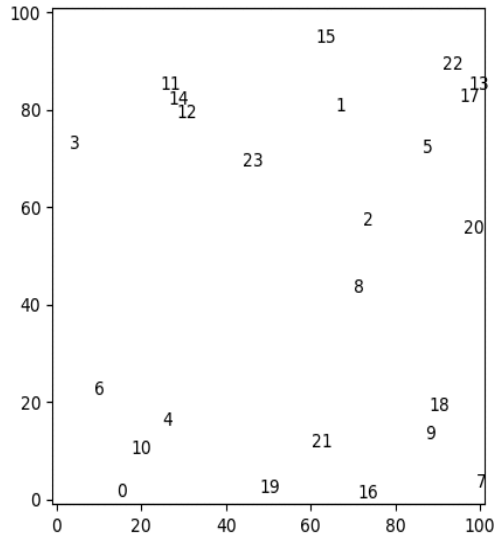
Add up all the Volumes  
to get **Total Volume**



|          | No. Of Vertices Of 2D Mesh | No. of Faces Of 2D Mesh | No. Of Vertices Of 3D Mesh | No. Of Faces Of 3D Mesh | No. of Tetrahedrons/ Voxels | Volume                     |
|----------|----------------------------|-------------------------|----------------------------|-------------------------|-----------------------------|----------------------------|
| Sphere   | 642                        | 1280                    | 699                        | 1280                    | 1969                        | 4.152<br>(4.18879)         |
| Cylinder | 114                        | 224                     | 253888                     | 79418                   | 1500998                     | 783751.355<br>(785398.163) |
| Knight   | 2321                       | 4638                    | 93977                      | 13048                   | 370066                      | 25608.972                  |
| Person   | 4461                       | 8918                    | 786452                     | 89367                   | 789226                      | 732991.271                 |
| Cow      | 2903                       | 5804                    | 638971                     | 37827                   | 628321                      | 111562.498                 |



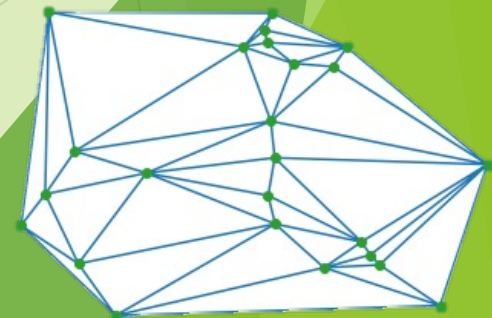
# Delaunay Tetrahedralization



Assume that  $V$  is a finite point set on a two-dimensional real number field, edge  $e$  is a closed line segment composed of points in the point concentration as the end point, and  $E$  is a set of  $e$ . Then a triangulation  $T=(V,E)$  of the point set  $V$  is a plane graph  $G$ , which satisfies the conditions:

- Except for the endpoints, the edges in the plane graph do not contain any points in the point set.
- There are no intersecting edges.
- All faces in the plan view are triangular faces, and the collection of all triangular faces is the convex hull of the scattered point set  $V$ .

- The most commonly used triangulation in practice is Delaunay triangulation, which is a special kind of triangulation that meet the following properties:
  - Delaunay triangulation is unique , in Delaunay triangulation there will be no other points within the circumcircle of any triangle
  - A triangle is formed by the three nearest points, and each line segment does not intersect.
  - No matter where the area starts from, the final result will be consistent.
  - If the diagonals of the convex quadrilateral formed by any two adjacent triangles are interchangeable, then the smallest angle among the six internal angles of the two triangles will not become larger.
  - if the smallest angle of each triangle in the triangulation is arranged in ascending order, the arrangement of the Delaunay triangulation will get the largest value.
  - Adding, deleting, or moving a vertex will only affect the adjacent triangle.
  - The outermost boundary of the triangular mesh forms a convex polygon shell.
- Many algorithms for computing Delaunay triangulations rely on fast operations for detecting when a point is within a triangle's circumcircle and an efficient data structure for storing triangles and edges.



# Mesh Generation Tools

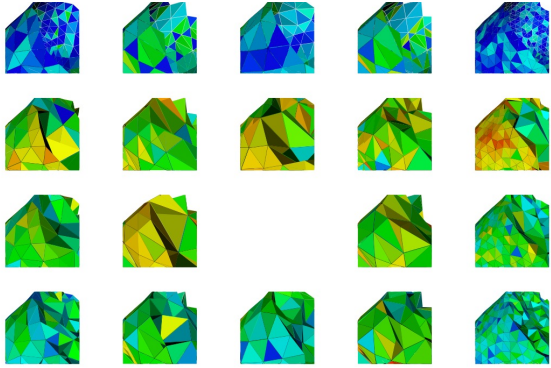


Figure 3: Silicon meshes from left to right: Afront, Macet, Dual Contouring, Marching Cubes, CGAL. Top to bottom: Surface mesh, zoomed surface mesh, TetGen, NetGen.

## ➤ TetGen

- TetGen is a suite of techniques used to generate different tetrahedral meshes from three-dimensional point sets or domains with piecewise linear boundaries.
- The algorithm it uses is called Constrained Delaunay Tetrahedralization (CDT).
- The TetGen implementation of the CDT is based on the incremental edge flipping algorithm.
- This algorithm preserves triangles in the boundary, thus making the edge flipping test very sensitive to the quality of the input mesh, and in some situations numerical problems are so severe that no CDT is generated.

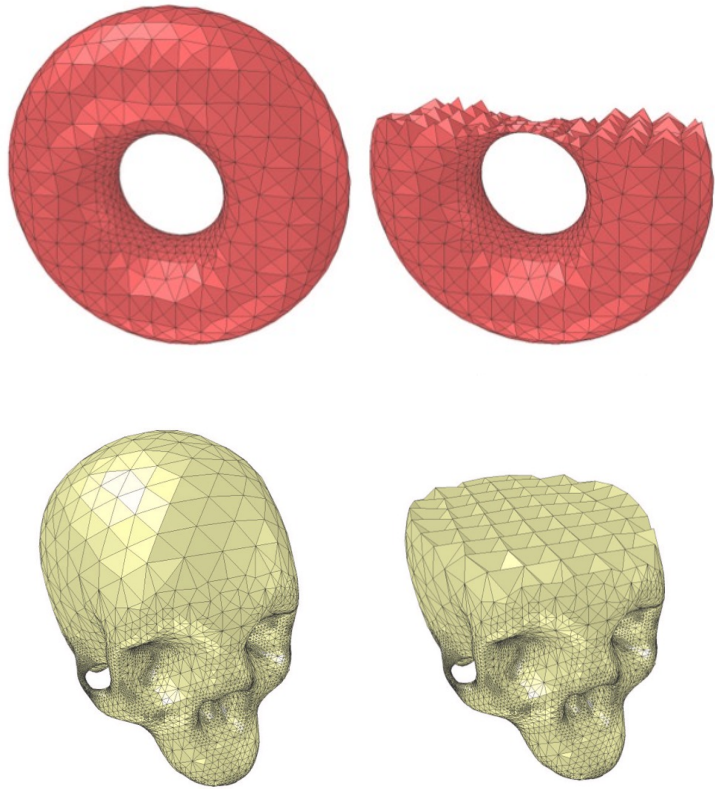
## ➤ NetGen

- NetGen is an automatic 3D advancing-front tetrahedral mesh generator that accepts input from constructive solid geometry (CSG) or boundary representations (BRep) from the STL file format.
- NetGen contains modules for mesh optimization and hierarchical mesh refinement.
- NetGen is open source for Unix/Linux and Windows.

## ➤ CAMAL

- The CUBIT Adaptive Meshing Algorithm Library (CAMAL) contains several of the CUBIT project's mesh generation algorithms.
- CUBIT's goal is robust and unattended mesh generation of complex geometries, scalable to millions of elements and thousands of parts.
- CUBIT is best known for its pioneering work on automated quadrilateral and hexahedral mesh generation, but also maintains robust triangle and tetrahedral meshing technologies.
- The tetrahedral mesh generation tool included in CAMAL is TetMesh-GHS3D, a package to automatically create tetrahedral meshes from closed triangular surface meshes, with little or no user interaction.
- The implementation is based on the algorithm that corresponds to another variation of a Constrained Delaunay Triangulation, and is, therefore, sensitive to the quality of the input mesh and may be prone to generate tetrahedral meshes with slivers if the boundary mesh does not maintain high quality.

# Tools Used and References



- ▶ SolidWorks
- ▶ MeshLab
- ▶ Python Library - PyMesh
- ▶ C++ Library - TetGen
- ▶ <http://www.sci.utah.edu/publications/lizier08/meshing-comp.pdf>
- ▶ <https://graphics.stanford.edu/papers/meshing-sig03/meshing.pdf>
- ▶ <https://towardsdatascience.com/delaunay-triangulation-228a86d1ddad>